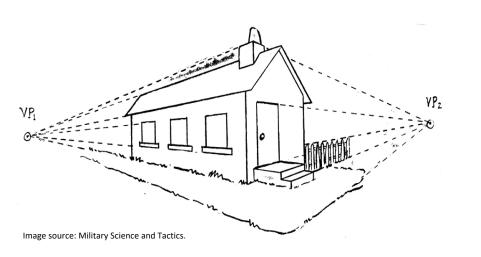


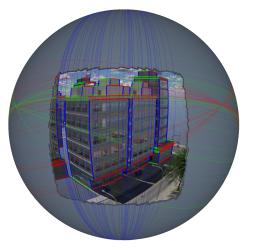


https://github.com/zhou13/neurvps

Vanishing Point Detection

- After perspective projection, parallel lines intersect at the same point, i.e., the vanishing point;
- Vanishing points bridge 2D and 3D by giving the 3D **line direction** in camera space from a single 2D image.





Applications



- (a) 3D Wireframe Lifting
- (b) Camera Calibration



(c) Photo Forensics

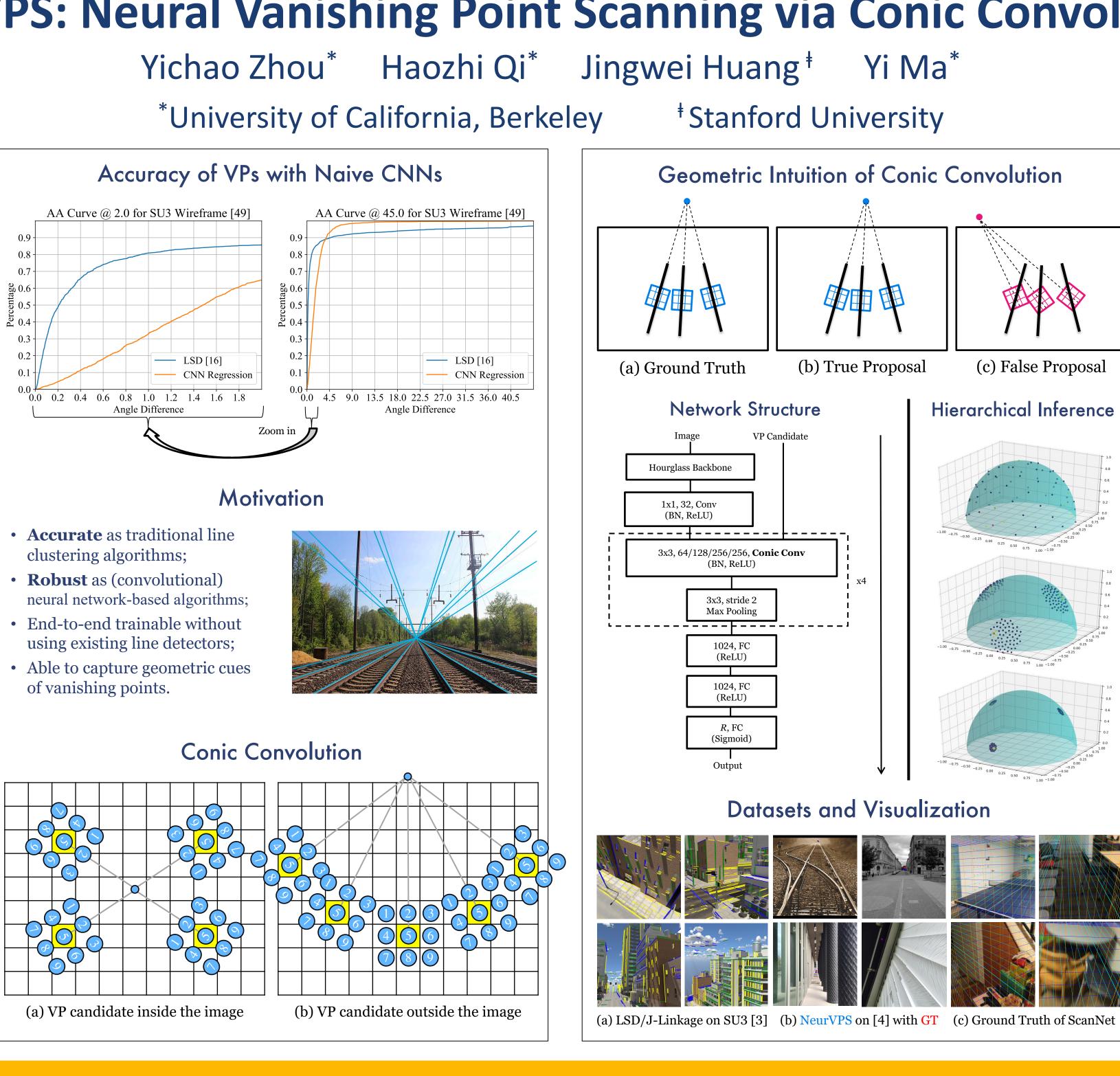
Related Work

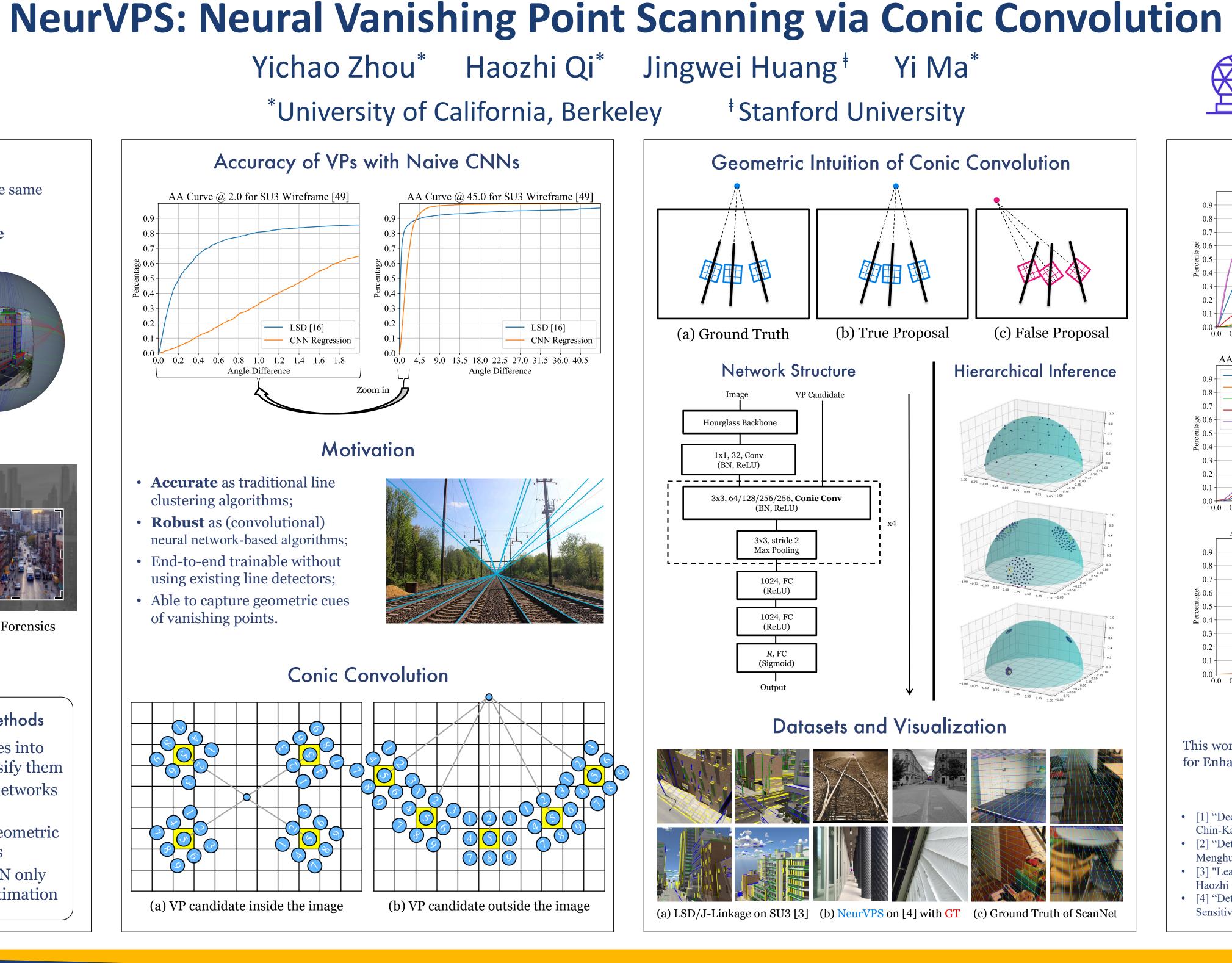
Traditional Methods

- Two-stage algorithms
- First, extract line segments from images
- Next, cluster lines based on their intersections
- Not end-to-end trainable
- Accurate, but outliers may result in total failure

CNN-Based Methods

- [1]: Divide images into patches and classify them
- [2]: Use neural networks to filter outlies
- Hard to utilize geometric properties of VPs
- **Robust**, but CNN only gives a coarse estimation





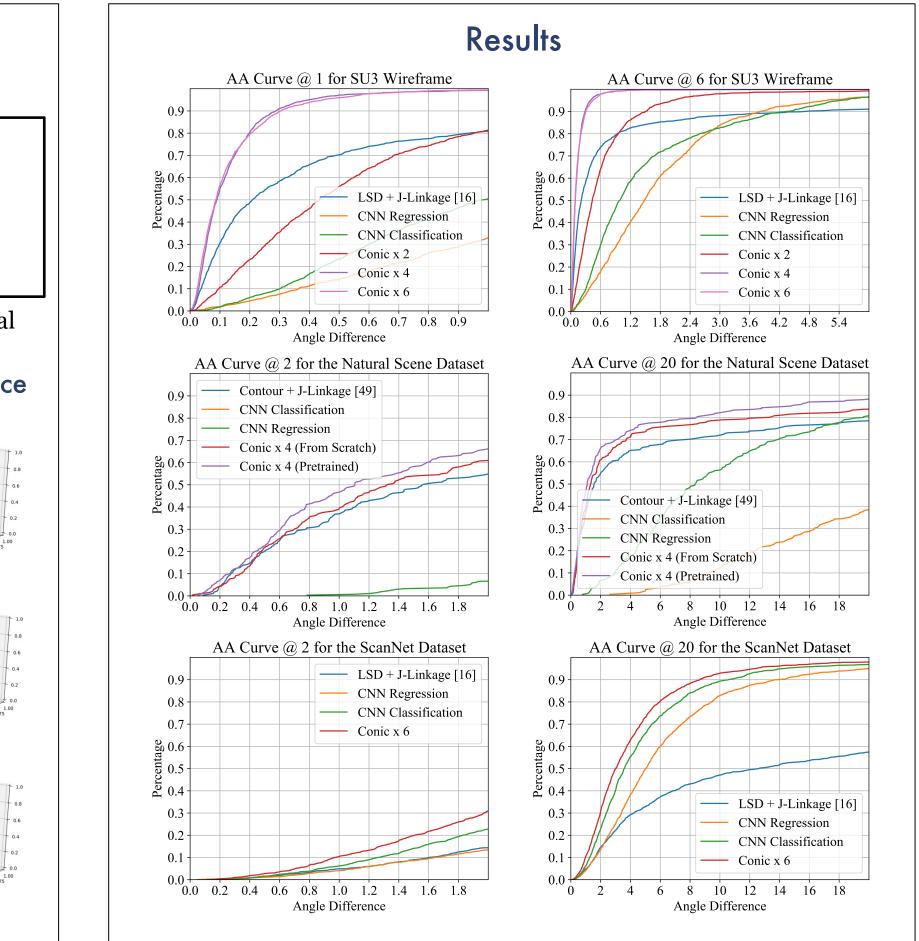


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